

Intersection Graphs in Simultaneous Embedding with Fixed Edges

*Michael Jünger*¹ *Michael Schulz*¹

¹Department of Computer Science, University of Cologne

Abstract

We examine the simultaneous embedding with fixed edges problem for two planar graphs G_1 and G_2 with the focus on their intersection $S = G_1 \cap G_2$. In particular, we will present the complete set of intersection graphs S that guarantee a simultaneous embedding with fixed edges for (G_1, G_2) . More formally, we define the subset $\mathcal{I}_{\text{SEFE}}$ of all planar graphs as follows: A graph S lies in $\mathcal{I}_{\text{SEFE}}$ if every pair of planar graphs (G_1, G_2) with intersection $S = G_1 \cap G_2$ has a simultaneous embedding with fixed edges. We will characterize this set by a detailed study of topological embeddings and finally give a complete list of graphs in this set as our main result of this paper.

Submitted: March 2009	Reviewed: June 2009	Revised: July 2009	Accepted: July 2009
	Final: July 2009	Published: July 2009	
Article type: Regular paper		Communicated by: S. G. Kobourov	

1 Introduction

A simultaneous embedding with fixed edges (SEFE) of two graphs G_1 and G_2 is a pair of drawings \mathcal{D}_1 of G_1 and \mathcal{D}_2 of G_2 such that each drawing is planar and the intersection $S = G_1 \cap G_2$ is drawn equally in both drawings. It is clear by definition that both graphs G_1 and G_2 need to be planar to allow a simultaneous embedding with fixed edges. However, not every pair of planar graphs has a simultaneous embedding with fixed edges. The problem to decide whether a graph pair has a simultaneous embedding with fixed edges or not has been studied from different angles. Erten and Kobourov [3] showed that any pair of a tree and a path always has a simultaneous embedding with fixed edges. Di Giacomo and Liotta [2] extended this result by showing that any pair of an outerplanar graph with a cycle has a simultaneous embedding with fixed edges while Frati [6] showed that any pair of a planar graph and a tree has a simultaneous embedding with fixed edges. Fowler et al. [5] used Frati's result as a starting point to characterize the set of planar graphs that have a simultaneous embedding with fixed edges with any planar graph in two ways: by a forbidden minor and by a complete list of graphs with this property. It turns out that any planar graph and any forest have a simultaneous embedding with fixed edges but there exist pairs of planar graphs and pseudo-forests without a simultaneous embedding with fixed edges. It could be shown [4] that the problem for this specific set of graph pairs can be decided in linear time. The corresponding problem for three general graphs is NP-complete [7].

So far, all examinations concerning the simultaneous embedding with fixed edges decision problem are of the same type. Restrict G_1 and/or G_2 to certain classes of planar graphs and then make a statement whether any pair of these graph types has a simultaneous embedding with fixed edges or not. In this paper we examine the simultaneous embedding with fixed edges problem for two planar graphs G_1 and G_2 from a different point of view. We focus on the intersection graph $S = G_1 \cap G_2$. Rather than forcing G_1 or G_2 to be a specific graph we examine which types of intersections allow a simultaneous embedding with fixed edges for general graphs G_1 and G_2 . In fact, we will present the complete set of intersection graphs S that guarantees a simultaneous embedding with fixed edges for (G_1, G_2) . More formally, we define the subset $\mathcal{I}_{\text{SEFE}}$ of all planar graphs as follows: A graph S lies in $\mathcal{I}_{\text{SEFE}}$ if every pair of planar graphs (G_1, G_2) with intersection $S = G_1 \cap G_2$ has a simultaneous embedding with fixed edges. We will present a complete list of graphs in this set as our main result.

So far, the SEFE problem has been mainly studied for the case that both graphs G_1 and G_2 have the same node set $V(G_1) = V(G_2)$. To our knowledge only Di Giacomo and Liotta [2] explicitly consider the case for special graph pairs with different node sets. However, the list of obtained results which require same node sets can be extended to the case where the node sets are different. In this paper, we loosen the restriction of equal node sets. This condition is irrelevant for most of our examinations but leads to a nice formulation of our main result as it is described in Theorem 5.

2 Preliminaries

A *combinatorial embedding* of a planar graph G is defined as a clockwise ordering of the incident edges for each node with respect to a crossing-free drawing of G in the plane. A *planar embedding* is a combinatorial embedding together with a fixed *external face*.

If a graph G is 2-connected, its *SPQR-tree* T represents the decomposition of G into its 3-connected components comprising serial, parallel, and 3-connected structures; see [1] for a formal definition. The respective structure is given by a skeleton graph associated with each tree node which is either a cycle (S-node), a bundle of parallel edges (P-node), or a 3-connected simple graph (R-node). In addition, Q-nodes serve as representatives for the edges of G .

If G is 2-connected and planar, its SPQR-tree T represents all combinatorial embeddings of G . In particular, a combinatorial embedding of G uniquely defines a combinatorial embedding of each skeleton in T , and fixing the combinatorial embedding of each skeleton uniquely defines a combinatorial embedding of G .

A tree with one node of degree k while all other nodes have degree 1 or 2 is called a *degree- k spider*. The union of a cycle and a path that share exactly one end-node of the path is a *degree-3 pseudo-spider*, see Figure 1.

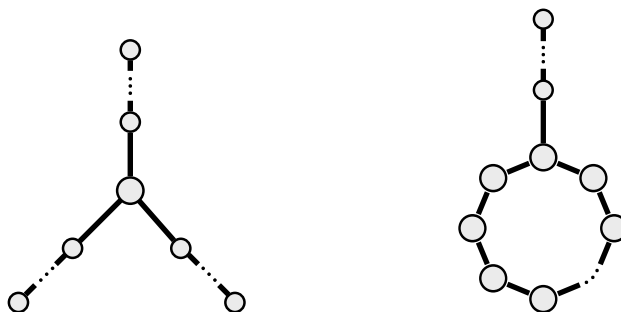


Figure 1: Visualizations of a degree-3 spider (left) and a degree-3 pseudo-spider (right).

Hershberger and Suri [8] present an algorithm for the *Euclidean Shortest Path Problem*. The problem consists of the computation of a shortest path between two points in the plane in the presence of polygonal obstacles. If n is the number of vertices in the obstacles, the algorithm runs in $O(n \log n)$ time which is proven to be optimal. In this paper we use this *Euclidean Shortest Path Algorithm* to route edges through an existing planar subdrawing in order to maintain planarity for the whole drawing. This can be done for edges whose endpoints lie on one face of the already existing subdrawing without inserting new crossings.

3 Combinatorial embeddings

We start by considering all connected planar graphs that have at most two combinatorial embeddings in order to use them as building blocks for our intersection graphs.

Lemma 1 *Let G be a connected planar graph that has exactly one combinatorial embedding. Then G is a path or a cycle.*

Proof: Every node of degree at least 3 can have multiple clockwise orders of its incident edges. Hence, G has only nodes of degree at most 2 and is either a path or cycle. \square

Theorem 1 *Let G be a connected planar graph that has exactly two combinatorial embeddings. Then G is*

- *a degree-3 spider,*
- *a degree-3 pseudo-spider,*
- *a subdivision of $K_4 \setminus \{e\}$, or*
- *a subdivision of a 3-connected graph with at least four nodes.*

Proof: Assume first that G does not have any non-trivial 2-connected component. Then G is a tree. Every node of degree d can have $(d-1)!$ many clockwise orders of its incident edges. As the number of combinatorial embeddings of G is given by the product of all these numbers $(d-1)!$, G has exactly one node of degree 3 and no node with larger degree. Hence, G is a degree-3 spider.

Let now B be a 2-connected component of G . Each cut-vertex can have multiple clockwise orders of its incident edges even if a combinatorial embedding of B is fixed (cf. Figure 2). Hence, there is at most one cut-vertex v of B and it has at most one incident edge not belonging to B . If $G \setminus B$ is not empty, the induced subgraph of $(G \setminus B) \cup \{v\}$ is connected, has exactly one planar embedding and a node with degree 1. By Lemma 1 this subgraph is a path. Even more, in this situation B has a unique combinatorial embedding and, again by Lemma 1, is a cycle. Hence, G is a degree-3 pseudo-spider.

From now on, G is biconnected. Let \mathcal{T} be the SPQR-tree of G . There is a bijection between the combinatorial embeddings of G and the set of combinatorial embeddings of the skeletons of each node in \mathcal{T} . Each R-node has two planar embeddings, each P-node has $(k-1)!$ planar embeddings where k is the number of parallel edges in the corresponding skeleton, and each S- and each Q-node has only a single planar embedding. As G has two planar embeddings, \mathcal{T} has exactly one P- and no R-node or no P- and one R-node. Furthermore, if there exists a P-node, its skeleton has exactly three parallel edges.

As any S-node in \mathcal{T} yields a subdivision of the corresponding edge, we see that G is a subdivision of the skeleton graph of the R- or P-node. If \mathcal{T} contains

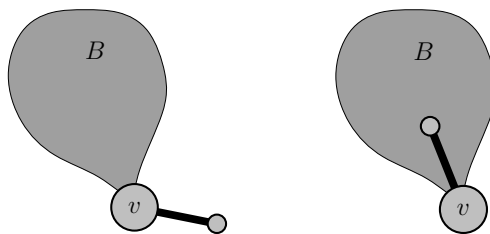


Figure 2: A cut-vertex v of a 2-connected component B can have multiple clockwise orders even if a combinatorial embedding of B is fixed.

exactly one R- and no P-node, the graph G is a subdivision of a 3-connected graph that has at least four nodes. If \mathcal{T} contains no R-node but exactly one P-node whose skeleton has three parallel edges, then G is a subdivision of $K_4 \setminus \{e\}$. In this case, at least two of the three parallel skeleton edges need to be subdivided to avoid parallel edges in the simple graph G . \square

An equivalent formulation of the graphs described in Theorem 1 is given in the following corollary. Here, the close connection of the first three graph types is taken into account.

Corollary 2 *Let G be a connected planar graph that has exactly two combinatorial embeddings. Then G is a subdivision of*

- $K_4 \setminus \{e_1, e_2, e_3\}$ where e_1, e_2, e_3 form a cycle,
- $K_4 \setminus \{e_1, e_2\}$ where e_1, e_2 form a path,
- $K_4 \setminus \{e\}$, or
- a 3-connected graph with at least four nodes.

Proof: On the one hand, it is easy to see that $K_4 \setminus \{e_1, e_2, e_3\}$ where e_1, e_2, e_3 form a cycle is a degree-3 spider. Further, $K_4 \setminus \{e_1, e_2\}$ where e_1, e_2 form a path is a degree-3 pseudo-spider.

On the other hand, these two graphs are the smallest degree-3 spider and smallest degree-3 pseudo-spider possible and any other degree-3 spider and degree-3 pseudo-spider is a subdivision of the two, respectively. \square

4 Topological embeddings

A combinatorial embedding of a planar graph defines the clockwise order of each node and hence the faces in each drawing. However, the relative positions of the connected components are not specified. This implies that two planar drawings of the same graph under the same planar embeddings may not be the same from a topological point of view (cf. Figure 3).

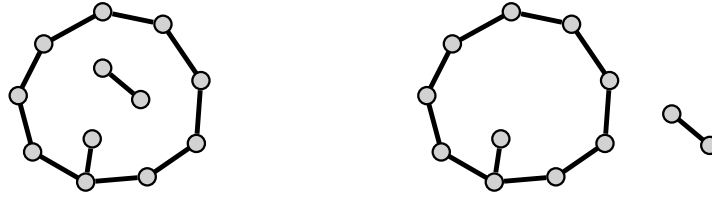


Figure 3: A disconnected graph may have different drawings from a topological point of view under the same planar embedding.

Let G be a planar graph and C be the set of its connected components. Given a set of planar embeddings, one for each $c \in C$, and a set of outer faces, one for each $c \in C$, we get a set IF of the inner faces of all connected components. From a topological point of view, $|IF| + 1$ is the number of regions in any planar drawing of G . Let $F = IF \cup \{o\}$ be the disjoint union of all inner faces and the global outer face o . We construct a directed, bipartite auxiliary graph $H = (V_H, E_H)$ with $V_H = F \cup C$. Each node $v \in IF \subseteq V_H$ has one outgoing edge pointing to its connected component $w \in C \subseteq V_H$. Each node $w \in C \subseteq V_H$ has one outgoing edge pointing to an element of $F \subseteq V_H$. This is the face where this connected component is inserted in a planar drawing. Hence, every planar drawing of G uniquely defines an auxiliary graph H . Furthermore, H has a special property: It contains no directed cycle and contains exactly one sink, i.e., a node with no outgoing edge. It is easy to see that each auxiliary graph H constructed like this uniquely defines a topological equivalence class of planar drawings of G .

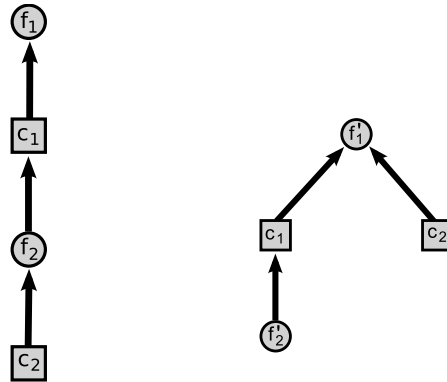


Figure 4: Auxiliary graphs for the topological embeddings shown in Figure 3. c_2 is the connected component given by the path of length 2, while c_1 is the other connected component. f_1 and f'_1 are the exterior face of c_1 , respectively, (and hence the global outer face) and f_2 and f'_2 its interior face, respectively.

For a planar graph G with a set C of connected components, we define a *topological embedding* of G by a set of combinatorial embeddings, one for each $c \in C$, a set of outer faces, one for each $c \in C$, and a directed, acyclic auxiliary graph H as defined above. For a connected graph G , H is a tree of depth 2 with all inner faces having an edge pointing to the only connected component that has an edge pointing to the outer face. Hence, a combinatorial embedding of a connected graph G , together with the choice of an outer face, is a topological embedding of G .

A topological embedding \mathcal{E} of a planar graph G uniquely determines a topological embedding $\mathcal{E}|_S$ for every subgraph $S \subseteq G$. *Mirroring* a given topological embedding of a planar graph G , that is mirroring all combinatorial embeddings of the individual connected components, yields again a topological embedding of G . The mirror image of an embedding of a cycle just swaps the two faces. It is easy to see that the topological subgraph embedding $\mathcal{E}|_S$ of a mirror image is the mirror image of the topological embedding $\mathcal{E}|_S$ for every subgraph S . A planar drawing \mathcal{D} of G respects \mathcal{E} if for each connected component c , the corresponding sub-drawing respects the corresponding combinatorial embedding including the choice of the outer face and the placement of the sub-drawings of the connected components is the same as defined by the auxiliary graph H . Such a topological embedding contains a unique outer face. Just like the choice of an outer face for a connected graph is independent from the choice of the combinatorial embedding, we define an equivalence class of topological embeddings that are the same topological embedding modulo the choice of the outer face.

Let \mathcal{E} be a topological embedding of some graph G , o its outer face and f some inner face. We show how to construct a topological embedding of G with outer face f . The auxiliary graph H is acyclic, has one sink o and each other node has one outgoing edge. Hence, there exists a unique directed path from f to o : $f = f_1 \rightarrow c_1 \rightarrow f_2 \rightarrow \dots \rightarrow c_k \rightarrow o$. We swap all edges in this path to construct $o \rightarrow c_k \rightarrow \dots \rightarrow f_2 \rightarrow c_1 \rightarrow f_1 = f$. This way, we create a different auxiliary graph H' that has the same properties as the first: It has one sink, no cycles, and each node except the new sink f has one outgoing edge. For all components c_i , $i = 1, \dots, k$, in the path we change the outer face from f_{i+1} to f_i , a former inner face. This uniquely defines another topological embedding of G that is, besides the choice of the outer face, the same as \mathcal{E} .

As the outer face of each connected component is encoded in the auxiliary graph, we can define the following equivalence class of topological embeddings: Two topological embeddings are equivalent if for each component the planar embedding is the same, as well as the undirected auxiliary graph. For a connected graph G , an equivalence class of topological embeddings is a combinatorial embedding without the choice of an outer face.

As a next result, we present a list of planar graphs that have at most two topological embeddings modulo the choice of an outer face. Here, we identify two topological embeddings of a graph to be equivalent if we can use the path technique defined above to get from one embedding to the other. The graph classes determined in Lemma 1 and Theorem 1 are the building blocks for the graphs with two topological embeddings.

Theorem 3 *A graph that has at most two topological embeddings, modulo the choice of an outer face, is*

- *the disjoint union of k paths with $k \geq 1$,*
- *the disjoint union of a single degree-3 spider and k paths with $k \geq 0$,*
- *the disjoint union of a cycle and at most one path,*
- *a degree-3 pseudo-spider,*
- *a subdivision of $K_4 \setminus \{e\}$, or*
- *a subdivision of a 3-connected graph with at least four nodes.*

Proof: We start by showing that all graphs from the list have at most two topological embeddings. The number of topological embeddings (modulo the choice of an outer face) is given by the product of the number of combinatorial embeddings for the connected components and the number of different placements for the connected components to each other. Each of the given graphs has at most one of these factors different from 1 and this factor is at most 2. For all but the union of a cycle and a path, the number of different placements for the connected components is 1 since either the graph is connected or it does not contain any cycle. In addition, at most one connected component has two combinatorial embeddings while all the others have only one combinatorial embedding. In the case of the union of a cycle and a path, both connected components have one combinatorial embedding and there are two different relative placements of the connected components to each other. Hence, in all cases there are at most two topological embeddings.

Next, we show that this list is the complete list of graphs with this property. Let G be a graph with at most two topological embeddings.

Every connected component has at most two combinatorial embeddings and is therefore, by Lemma 1 and Theorem 1, a path, a cycle, a degree-3 spider, a degree-3 pseudo-spider, a subdivision of $K_4 \setminus \{e\}$ or a subdivision of a 3-connected graph with at least four nodes.

Consequently, if G is connected, it is one of these graphs. Furthermore, if G is not connected, at most one connected component may have more than one combinatorial embedding and hence all but one connected component are paths or cycles.

Assume that G has three connected components c_1 , c_2 , and c_3 and at least one connected component, say c_1 , contains a cycle. Then c_1 has at least two faces f_1 and f_2 (where one may be the global outer face). c_2 and c_3 can be positioned both in f_1 , both in f_2 , or one in f_1 and one in f_2 , and this results in a list of at least three different topological embeddings. Hence, this situation may not occur and if G contains more than two connected components, it must be a forest. But then, it is a disjoint union of paths or a disjoint union of a single degree-3 spider and some number of paths since paths are the only trees

with a single planar embedding and degree-3 spiders are the only trees with two planar embeddings.

From now on, G has exactly two connected components c_1 and c_2 . We know already that one, say c_2 , is either a cycle or a path and the other, c_1 , is a path, a cycle, a degree-3 spider, a degree-3 pseudo-spider, a subdivision of $K_4 \setminus \{e\}$ or a subdivision of a 3-connected graph with at least four nodes. If c_1 has two combinatorial embeddings, the relative placement of the connected components to each other must be unique. Otherwise, we would have more than two topological embeddings by creating all combinations. But the component placement is unique only if there exists a single face, i.e., if G is a forest. Hence, c_1 cannot be a degree-3 pseudo-spider, a subdivision of $K_4 \setminus \{e\}$ or a subdivision of a 3-connected graph with at least four nodes. In addition, if c_1 is a degree-3 spider, c_2 cannot be a cycle but only a path.

It remains to check the case of two cycles, but here both connected components have two faces. Then, the different relative placements of the components to each other result in four cases, each leading to a larger number of topological embeddings. \square

It is easy to see that if a graph G has exactly two topological embeddings \mathcal{E}_1 and \mathcal{E}_2 , then \mathcal{E}_2 must be the mirror image of \mathcal{E}_1 . Whenever one connected component c of G is a graph of Theorem 1, the two topological embeddings differ only in the combinatorial embedding of c , so they are mirror images of each other. Otherwise, either G has only one topological embedding (when G is a single cycle or the union of paths) or G is a cycle and a path. But in this case, again, the two topological embeddings are mirror images of each other.

5 Compatible embeddings

We now focus on the SEFE problem for two planar graphs and start with the definition of compatible embeddings. Let G_1 and G_2 be two planar graphs with intersection $S = G_1 \cap G_2$ and let \mathcal{E}_i be topological embeddings of G_i for $i = 1, 2$. We call \mathcal{E}_1 and \mathcal{E}_2 *compatible embeddings* if $\mathcal{E}_1|_S = \mathcal{E}_2|_S$ where $\mathcal{E}_i|_S$ is the unique induced topological embedding of S . We will see next that the existence of compatible embeddings is directly linked to the existence of a simultaneous embedding with fixed edges.

Lemma 2 *Given a planar graph G , let \mathcal{E}_G be a planar embedding and \mathcal{D}' be a partial drawing that respects \mathcal{E}_G . We can extend \mathcal{D}' into a complete crossing-free drawing of G .*

Proof: We show how to extend \mathcal{D}' to a complete planar drawing of G by extending the partial drawing of \mathcal{D}' with a single edge at a time. Nodes that are not placed yet will be positioned somewhere in the faces according to \mathcal{E}_G keeping some ε distance to any node or edge within this face.

Let S be the subgraph of G that is already drawn. We start inserting those remaining edges of $G \setminus S$ that do not create new faces. Let $e = (v, w)$ be such

an edge. The end nodes v and w belong to different connected components of S as they would create a cycle (and hence a new face) otherwise. By the planar embedding \mathcal{E}_G both v and w lie on the same face f in \mathcal{D}' . Furthermore, the clockwise orderings of the incident edges of v and w in \mathcal{E}_G imply that the new edge will start and end in f . Hence, we can use the Euclidean Shortest Path Algorithm to route this edge through this face.

At some point every new edge creates a new face. However, we can choose an ordering of the remaining faces such that each edge closes one of the faces of \mathcal{E}_G . Let $e = (v, w)$ be such an edge and let P be the walk $(v = v_1, \dots, v_k = w)$ that together with e is the boundary of the corresponding face. Furthermore, let c_1, \dots, c_l be the connected components of G that lie in this face as given by (the auxiliary graph of) \mathcal{E}_G . We can draw e from v to w along P keeping an ε distance to P not enclosing any other nodes and not crossing any edge in the newly created face of \mathcal{D}' . Of course, the leaving direction of e in v and w is chosen according to the embedding \mathcal{E}_G .

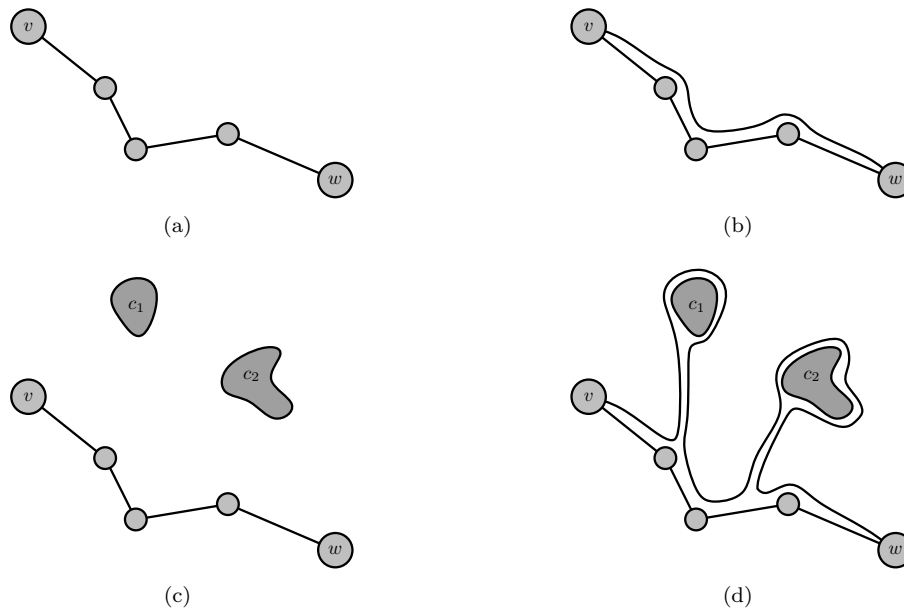


Figure 5: Possible routings of edge $e = (v, w)$. (a,b): The edge can be routed along the given path $(v = v_1, \dots, v_k = w)$ if there are no connected components that must lie in the newly created face. (c,d): However, for each connected component c_i this route can be extended by additional routes using the Euclidean Shortest Path Algorithm to the component and back.

However, for each component c_i , $i = 1, \dots, l$, at some point in our travel from v to w we stop to include c_i in the newly created face. This can be done by using the Euclidean Shortest Path Algorithm to route from our given position

to some point of c_i , then travel around c_i (again keeping an ε distance without enclosing any other node) and use the route found by the Euclidean Shortest Path Algorithm to come back to the original position on our route (again keeping an ε distance to the previous route). See Figure 5 for an example.

Using this approach for any edge, \mathcal{D}' respects \mathcal{E}_G and becomes a complete planar drawing of G . \square

Theorem 4 *Let G_1 and G_2 be two planar graphs. G_1 and G_2 have a simultaneous embedding with fixed edges if and only if there exists a pair of compatible embeddings of (G_1, G_2) .*

Proof: Let $(\mathcal{D}_1, \mathcal{D}_2)$ be a simultaneous embedding with fixed edges of (G_1, G_2) and let $(\mathcal{E}_1, \mathcal{E}_2)$ be the topological embeddings induced by $(\mathcal{D}_1, \mathcal{D}_2)$. As S is drawn equally in \mathcal{D}_1 and \mathcal{D}_2 , we get $\mathcal{E}_1|_S = \mathcal{E}_2|_S$ and consequently, $(\mathcal{E}_1, \mathcal{E}_2)$ is a pair of compatible embeddings.

Let $(\mathcal{E}_1, \mathcal{E}_2)$ be a pair of compatible embeddings of (G_1, G_2) . We show how to construct a pair of planar drawings $(\mathcal{D}_1, \mathcal{D}_2)$ of (G_1, G_2) that respect $(\mathcal{E}_1, \mathcal{E}_2)$ and yield a simultaneous embedding with fixed edges. Use \mathcal{E}_1 to construct a planar drawing of G_1 . This can be done by starting with the combinatorial embeddings of the connected components to construct planar drawings of these and then use the auxiliary graph to determine the placement of the connected components to each other. Enlarging or shrinking the drawings of the connected components to create enough space for the other components when necessary leads to a planar drawing \mathcal{D}_1 of G_1 .

Now let $S = G_1 \cap G_2$ and $\mathcal{D}'_2 = \mathcal{D}_1|_S$ be a drawing of S according to drawing \mathcal{D}_1 . But then \mathcal{D}'_2 is a partial drawing of G_2 that respects \mathcal{E}_2 and we can use Lemma 2 to construct a planar drawing \mathcal{D}_2 that respects \mathcal{E}_2 . As both \mathcal{D}_1 and \mathcal{D}_2 are planar drawings of G_1 and G_2 , respectively, with $\mathcal{D}_1|_S = \mathcal{D}_2|_S$, $(\mathcal{D}_1, \mathcal{D}_2)$ is a simultaneous embedding with fixed edges of (G_1, G_2) . \square

6 $\mathcal{I}_{\text{SEFE}}$

Compatible embeddings of a pair of graphs G_1 and G_2 are those topological embeddings that can be used to create a simultaneous embedding with fixed edges of G_1 and G_2 . Deciding whether a pair of graphs has a pair of compatible embeddings may not be easy in general. However, if we restrict the intersection of a graph pair, the requirement $\mathcal{E}_1|_S = \mathcal{E}_2|_S$ may be trivially satisfied for almost every pair of embeddings. Using this approach, we determine $\mathcal{I}_{\text{SEFE}}$, the set of all intersection graphs with a guaranteed simultaneous embedding with fixed edges for all graph pairs. We show that $\mathcal{I}_{\text{SEFE}}$ corresponds exactly to the set of graphs that we determined in Theorem 3.

Lemma 3 *Given two planar graphs G_i , $i = 1, 2$, such that $S = G_1 \cap G_2$ has at most two topological embeddings that are mirror images of each other, then every pair of topological embeddings \mathcal{E}_i of G_i , $i = 1, 2$, yields a pair of compatible embeddings in which \mathcal{E}_2 is possibly mirrored.*

Proof: Let \mathcal{E}_i be any planar embedding of G_i for $i = 1, 2$. If \mathcal{E}_1 and \mathcal{E}_2 do not yield the same embedding $\mathcal{E}_1|_S = \mathcal{E}_2|_S$, we mirror \mathcal{E}_2 and the demanded equality holds and guarantees a pair of compatible embeddings. \square

The following theorem states our main result. Using the complete list of the planar graphs with at most two topological embeddings of Theorem 3, we show that this set of graphs is exactly the set \mathcal{I}_{SEFE} .

Theorem 5 \mathcal{I}_{SEFE} is the set of all planar graphs that have at most two topological embeddings.

Proof: Let S be a planar graph with at most two topological embeddings. Then these embeddings are mirror images of each other. If a pair of planar graphs G_1 and G_2 has the intersection $S = G_1 \cap G_2$, then Lemma 3 states that any pair $(\mathcal{E}_1, \mathcal{E}_2)$ of topological embeddings of (G_1, G_2) yields a pair of compatible embeddings by possibly mirroring \mathcal{E}_2 . In particular, G_1 and G_2 have a pair of compatible embeddings. But then Theorem 4 guarantees the existence of a simultaneous embedding with fixed edges.

Let S be a planar graph that has a pair of topological embeddings \mathcal{E}_1 and \mathcal{E}_2 that are not mirror images of each other. We show how to construct two graphs G_1 and G_2 with intersection $S = G_1 \cap G_2$ but without a simultaneous embedding with fixed edges. G_i is obtained by triangulating S while respecting the embedding \mathcal{E}_i . This straightforward graph transformation constructs a 3-connected graph G_i . It may happen that we add an edge e to G_1 and G_2 that would enlarge their intersection $G_1 \cap G_2$. If this is the case, we substitute e in G_2 with a path of length 2 by introducing a new node. This way we guarantee $G_1 \cap G_2 = S$. G_2 may not be 3-connected anymore but it becomes a subdivision of a 3-connected graph. Consequently, both graphs G_1 and G_2 are connected and have a unique planar embedding (up to mirroring). The unique induced topological embedding of S in G_i is \mathcal{E}_i (or its mirror image). Hence, by Theorem 4, G_1 and G_2 cannot have a simultaneous embedding with fixed edges as they have no pair of compatible embeddings. \square

An example for the construction of G_1 and G_2 as given in the proof to Theorem 5 is presented in Figure 6. Notice that the two resulting graphs G_1 and G_2 may have different node sets since we add dummy nodes in order to avoid increasing their intersection.

Corollary 6 A planar graph belongs to \mathcal{I}_{SEFE} if and only if it is one of the following:

- the disjoint union of k paths with $k \geq 1$,
- the disjoint union of a single degree-3 spider and k paths with $k \geq 0$,
- the disjoint union of a cycle and at most one path,
- a degree-3 pseudo-spider,
- a subdivision of $K_4 \setminus \{e\}$, or
- a subdivision of a 3-connected graph with at least four nodes.

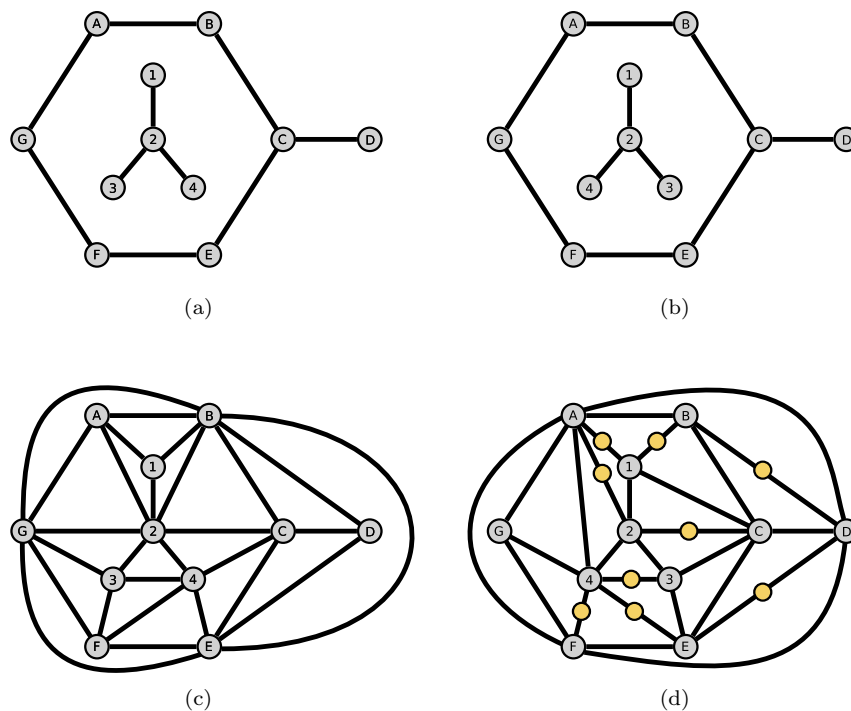


Figure 6: An example of how to construct a pair of graphs without simultaneous embedding with fixed edges from a pair of topological embeddings that are not mirror images of each other. (a) and (b) show an intersection graph S with different topological embeddings \mathcal{E}_1 and \mathcal{E}_2 . (c) and (d) show two connected graphs G_1 and G_2 with unique planar embeddings (up to mirroring and the choice of the outer face). Their intersection $G_1 \cap G_2 = S$ has the induced topological embeddings \mathcal{E}_1 and \mathcal{E}_2 , respectively.

7 Conclusion

In this paper we studied the simultaneous embedding with fixed edges problem for a graph pair (G_1, G_2) with a focus on the intersection graph $G_1 \cap G_2$. We defined $\mathcal{I}_{\text{SEFE}}$ as the set of all intersection graphs S that guarantee a simultaneous embedding with fixed edges for any pair (G_1, G_2) with $S = G_1 \cap G_2$. Using the new construction of compatible embeddings, we could characterize $\mathcal{I}_{\text{SEFE}}$ as the set of all planar graphs with at most two topological embeddings. Our detailed study of topological embeddings results in a complete list of all graphs in $\mathcal{I}_{\text{SEFE}}$.

References

- [1] G. Di Battista and R. Tamassia. On-line planarity testing. *SIAM Journal on Computing*, 25(5):956–997, 1996.
- [2] E. Di Giacomo and G. Liotta. Simultaneous embedding of outerplanar graphs, paths, and cycles. *Int. J. Comput. Geometry Appl.*, 17(2):139–160, 2007.
- [3] C. Erten and S. G. Kobourov. Simultaneous embedding of planar graphs with few bends. *Journal of Graph Algorithms and Applications*, 9(3):347–364, 2005.
- [4] J. J. Fowler, C. Gutwenger, M. Jünger, P. Mutzel, and M. Schulz. An SPQR-approach to decide special cases of simultaneous embedding with fixed edges. In I. G. Tollis and M. Patrignani, editors, *Graph Drawing '08*, volume 5417 of *Lecture Notes in Computer Science*, pages 157–168, 2009.
- [5] J. J. Fowler, M. Jünger, S. G. Kobourov, and M. Schulz. Characterizations of restricted pairs of planar graphs allowing simultaneous embedding with fixed edges. In H. Broersma, T. Erlebach, T. Friedetzky, and D. Paulusma, editors, *Workshop on Graph-Theoretical Concepts in Computer Science '08*, volume 5344 of *Lecture Notes in Computer Science*, pages 146–158, 2008.
- [6] F. Frati. Embedding graphs simultaneously with fixed edges. In M. Kaufmann and D. Wagner, editors, *Graph Drawing '06*, volume 4372 of *Lecture Notes in Computer Science*, pages 108–113, 2007.
- [7] E. Gassner, M. Jünger, M. Percan, M. Schaefer, and M. Schulz. Simultaneous graph embeddings with fixed edges. In F. V. Fomin, editor, *Workshop on Graph-Theoretical Concepts in Computer Science '06*, volume 4271 of *Lecture Notes in Computer Science*, pages 325–335, 2006.
- [8] J. Hershberger and S. Suri. An optimal algorithm for Euclidean shortest paths in the plane. *SIAM Journal on Computing*, 28(6):2215–2256, 1999.